

# Holomorphic Dynamics - Lecture 3

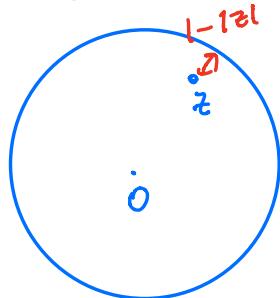
$$\mathbb{D} \simeq \mathbb{H}$$

$$\begin{matrix} \mathbb{C} \\ \hat{\mathbb{C}} \end{matrix}$$

## Poincaré disk

Thm There exists a unique Riemannian metric on  $\mathbb{D}$  which is invariant under  $\text{Aut}(\mathbb{D})$ .

It is given by  $ds = \frac{2|dz|}{1-|z|^2}$



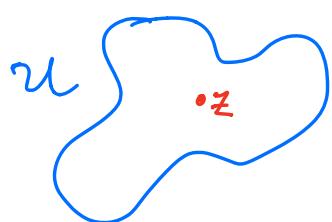
Rmk if  $|z| \sim 1$

$$\begin{aligned} ds &= \frac{2|dz|}{(1-|z|)(1+|z|)} = \frac{2}{1+|z|} \cdot \frac{|dz|}{1-|z|} \\ &\approx \frac{|dz|}{d_E(z, \partial\mathbb{D})} \end{aligned}$$

Infact: if  $U$  is simply connected open, proper subset of  $\mathbb{C}$ , then you can define a Poincaré metric on  $U$

$$U \xrightarrow{\varphi} \mathbb{D}$$

$$\rho_U = \varphi^* \rho_{\mathbb{D}}$$



$$ds \approx \frac{|dz|}{d_E(z, \partial U)}$$

Pf (sketch)

① if  $ds^2 = g_{11} dx^2 + 2g_{12} dx dy + g_{22} dy^2$  is invariant under  $\text{Aut}(\mathbb{D})$

then at  $z=0$

$$ds^2 = g_{11} (dx^2 + dy^2)$$

(applying invariance by rotation)

$\Rightarrow$   $ds$  is CONFORMAL

i.e.  $\exists \rho: \mathbb{D} \rightarrow \mathbb{R}^{>0}$  s.t.

$$ds = \rho(z) dz$$

② if  $ds = \rho(z) dz$  is invariant by  $\gamma \in \text{Aut}(\mathbb{D})$ , then:

$$z' = \gamma(z)$$

$$\rho(\gamma(z)) \gamma'(z) dz = \rho(z) dz$$

$$\rho(\gamma(z)) = \frac{\rho(z)}{\gamma'(z)} \quad \text{for all } z \in \mathbb{D}.$$

in upper half plane model

$$\rho(\gamma(z)) = \frac{\rho(z)}{\gamma'(z)} \quad \text{for all } z \in \mathbb{H}$$

$$\gamma(z) = a + bz \quad (b > 0)$$

$$\rho(a+bz) = \frac{\rho(z)}{b} \quad \rho(i) = 1 \quad \forall a, b > 0, \forall z \in \mathbb{H}$$

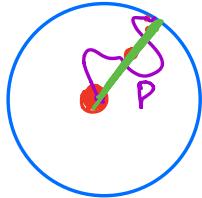
$$\rho(a+bi) = \frac{1}{b} \rho(i) = \frac{1}{b}$$

$$ds = \frac{dz}{\operatorname{Im}(z)} = \frac{dz}{y} \quad (z = x+iy)$$

Lemma 2 The disk  $\mathbb{D}$  with the Poincaré metric is complete. Moreover:

- ① any path from a point in  $\mathbb{D}$  to a point in  $\partial\mathbb{D}$  has infinite length
- ② every two points are joined by a unique geodesic.

Pf



Pick path inside  $\mathbb{D}$ :

$$\int_P ds = \int_P \frac{2|dz|}{1-|z|^2} \geq \int_0^1 \frac{2}{1-r^2} dr$$

$$\int_0^1 \frac{2 dr}{1-r^2} = \int_{1-r}^1 \frac{dr}{r} + \int_{1+r}^1 \frac{dr}{r} = \log\left(\frac{1+r}{1-r}\right) \quad \downarrow r \rightarrow r$$

$\infty$

Thm (Schwarz, Pick, Ahlfors)

If  $f: \mathbb{D} \rightarrow \mathbb{D}$  is holomorphic, then

$$s_{\mathbb{D}}(f(x), f(y)) \leq s_{\mathbb{D}}(x, y) \quad \forall x, y \in \mathbb{D}$$

and if you have equality at some points then  $f$  must be an isometry.

Pf if  $x=0=f(x)$ , then Schwarz lemma  
otherwise, apply  $\gamma \in \text{Aut}(\mathbb{D})$  to reduce  
to that situation (use invariance of metric).

Riemann sphere

$$\hat{\mathbb{C}} = \mathbb{C} \cup \{\infty\}$$

carries a spherical metric

$$ds = \frac{2|dz|}{1 + |z|^2}$$

has constant curvature  $K \equiv +1$ .

$$\text{Aut}(\widehat{\mathbb{C}}) = \left\{ z \mapsto \frac{az+b}{cz+d}, \begin{matrix} a,b,c,d \in \mathbb{C} \\ ad-bc \neq 0 \end{matrix} \right\}$$

$$= \cancel{SL_2(\mathbb{C})} \simeq PSL_2(\mathbb{C})$$

Classification of elements of

$PSL_2(\mathbb{R})$

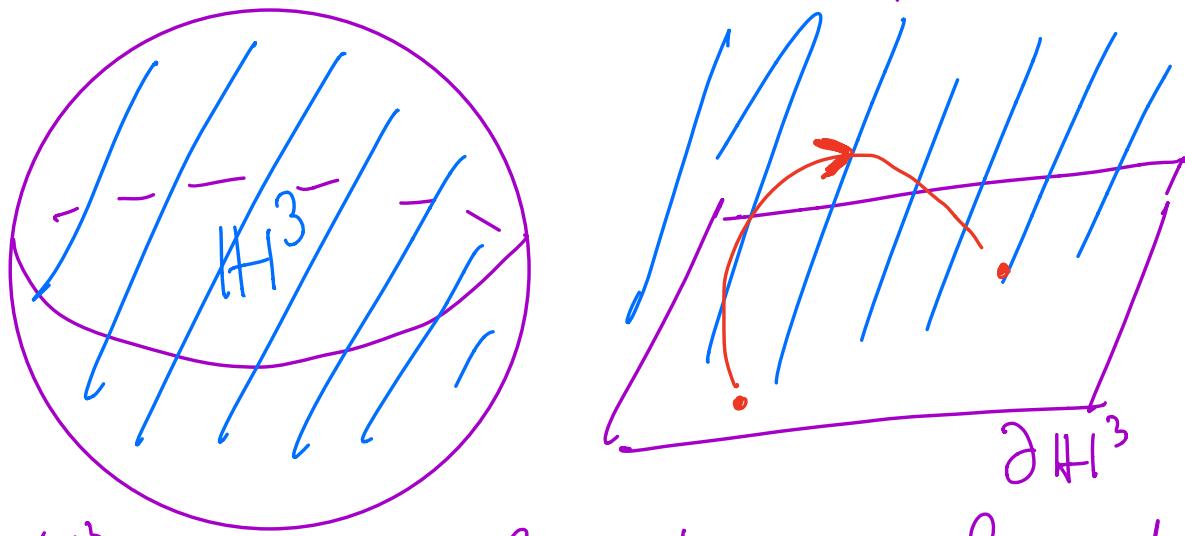
$z \mapsto -\frac{1}{z}$  elliptic  $|\text{tr } A| < 2$   
 it has a fixed point inside  $\mathbb{H}$

$z \mapsto z + 1$  parabolic  $|\text{tr } A| = 2$   
 it has a fixed point on  $\partial \mathbb{H}$

$z \mapsto \lambda z$  loxodromic/hyperbolic  $|\text{tr } A| > 2$

( $\lambda > 1$ ) has two fixed points on  $\partial \mathbb{H}$

Recall  $PSL_2(\mathbb{C}) \cong \text{Isom}^+(\mathbb{H}^3)$



In  $\mathbb{H}^3$  picture, a loxodromic element of  $PSL_2(\mathbb{C})$  acts by translating AND rotating around the geodesic.

Note :

- ① if an elt of  $PSL_2(\mathbb{C})$  fixes 3 points of  $\hat{\mathbb{C}}$ , it is the identity.

$$z = \frac{az+b}{cz+d}$$

- ② every elt of  $PSL_2(\mathbb{C})$  has at least one fixed point.

Cor.: The sphere does not cover any other Riemann surface.

Pf if  $S$  has  $\hat{\mathbb{C}}$  as its univ. cover,

then  $\hat{\mathbb{C}} \xrightarrow{\sim} S$

$S = \frac{\hat{\mathbb{C}}}{\Gamma}$  where  $\Gamma < \text{Aut}(\hat{\mathbb{C}})$   
discrete, fixed point  
free subgroup

But every eft has at least a fixed point, hence  $\Gamma = \{1\}$ .

## EUCLIDEAN PLANE

$\mathbb{C}$  carries a flat metric  
 $dz$        $K=0$

$$\text{Aut}(\mathbb{C}) = \{z \mapsto az+b, a \neq 0, a, b \in \mathbb{C}\}$$

Riemann surfaces whose universal cover is  $\mathbb{C}$

$$S = \mathbb{C} / \Gamma$$

$$\Gamma < \text{Aut}(\mathbb{C})$$

discrete  
fixed point  
free

$$z \mapsto az + b \quad \text{must have } \underline{a=1}$$

$$z \mapsto z + b$$

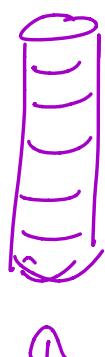
$$\textcircled{1} \quad \Gamma = \{1\}, \quad S = \mathbb{C}$$

$$\textcircled{2} \quad \Gamma = \langle z \mapsto z + 1 \rangle$$

$$S = \mathbb{C} / \overline{\langle z \mapsto z + 1 \rangle}$$

cylinder  
carries a  
flat metric

$$\mathbb{C} / \mathbb{Z}$$

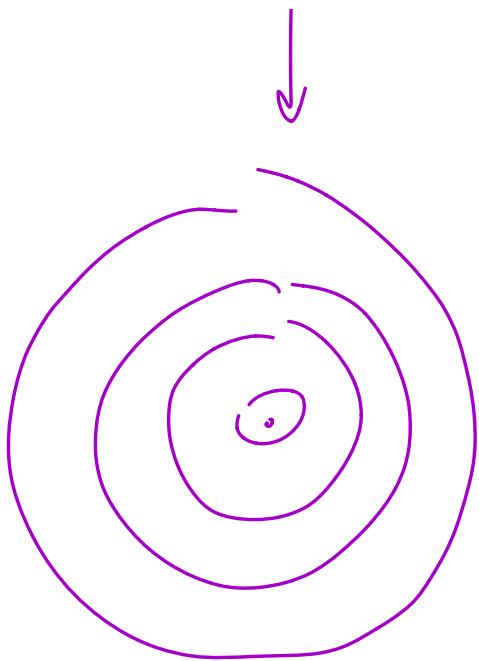


$$\mathbb{C} \setminus \{0\}$$

$$\mathbb{C} \xrightarrow{\exp(2\pi i z)} \mathbb{C} \setminus \{0\}$$

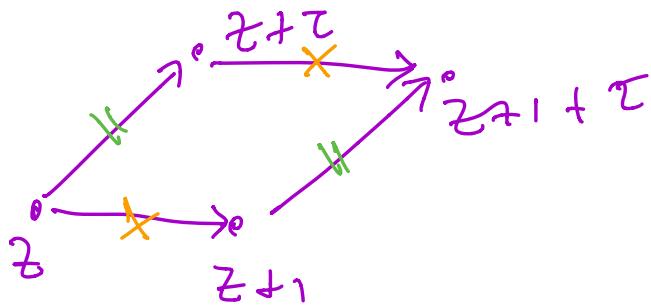
$$\exp(2\pi i(z+1)) = \exp(2\pi i z)$$

$$\mathbb{C}/\mathbb{Z} \xrightarrow{\sim} \mathbb{C} \setminus \{0\}$$



$$③ \quad \Gamma = \langle z \mapsto z+1, z \mapsto z+\tau \rangle$$

$$\operatorname{Im} \tau > 0$$



$\mathbb{C}/\Gamma$  torus

Riemann surfaces whose universal cover is  $\mathbb{D}$

(HYPERBOLIC SURFACES)

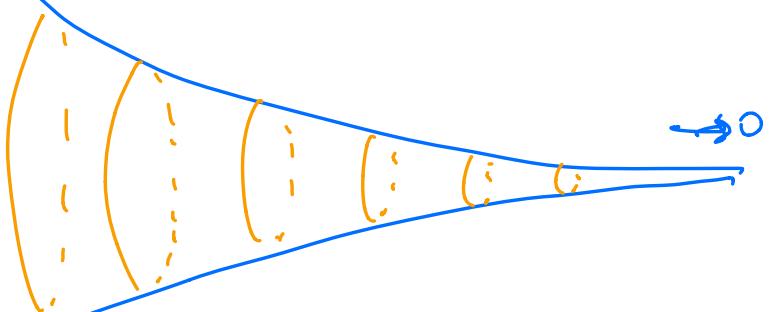
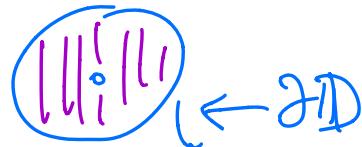
$$S = \frac{\mathbb{D}}{\Gamma}$$

z ↦ 1/z

$\Gamma < \operatorname{Aut}(\mathbb{D}) \cong \operatorname{PSL}_2(\mathbb{R})$   
fixed point free

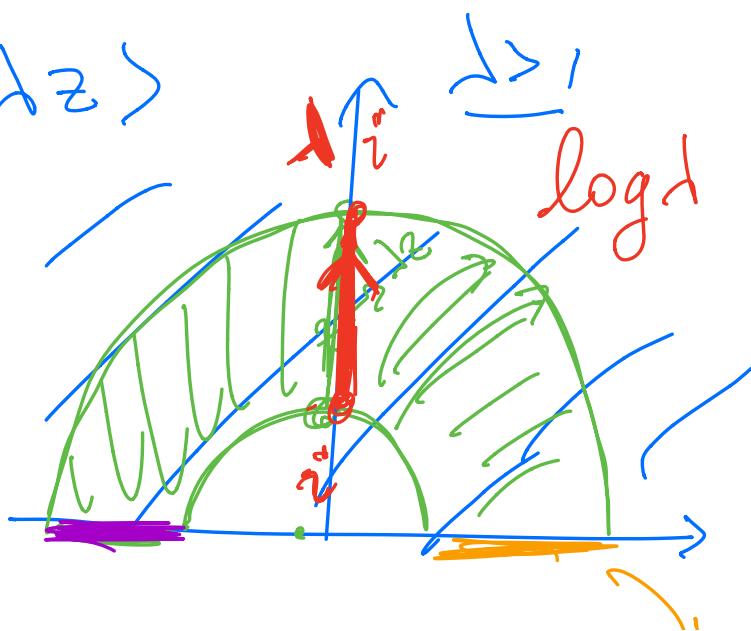
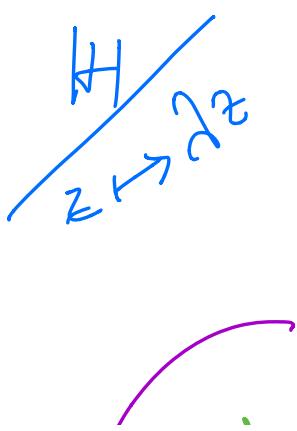
All such  $\gamma$  carry a Poincaré metric

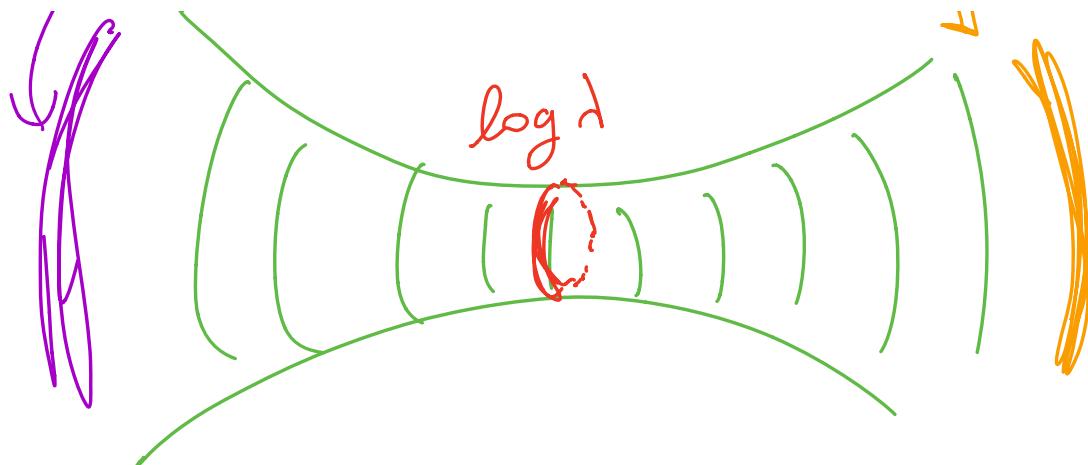
$$\Gamma = \langle z \mapsto z + 1 \rangle$$



$$H \xrightarrow{\exp(2\pi i z)} D \setminus \{0\}$$

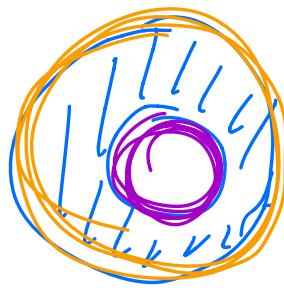
$$\Gamma = \langle z \mapsto \lambda z \rangle$$





$$A_R = \{ z : 1 < |z| < R \}$$

$$\begin{array}{ccc} \mathbb{H} & \xrightarrow{\pi} & A_R \\ z \mapsto \lambda z & & \end{array}$$



$$\pi(z) = \pi(\lambda z)$$

$$\pi(z) = \exp\left(\frac{2\pi i}{\log \lambda} \log(z)\right)$$

$$2\pi i \frac{\log(\lambda z)}{\log \lambda} = 2\pi i + 2\pi i \frac{\log z}{\log \lambda}$$

$$\begin{array}{c} \sigma \\ z > 0 \\ \hline z < 0 \end{array} \quad \pi(\mathbb{R}^+) = S^1$$

$$\pi(z) = \exp\left(\frac{2\pi i}{\log \lambda} (i\pi + \log|z|)\right) =$$

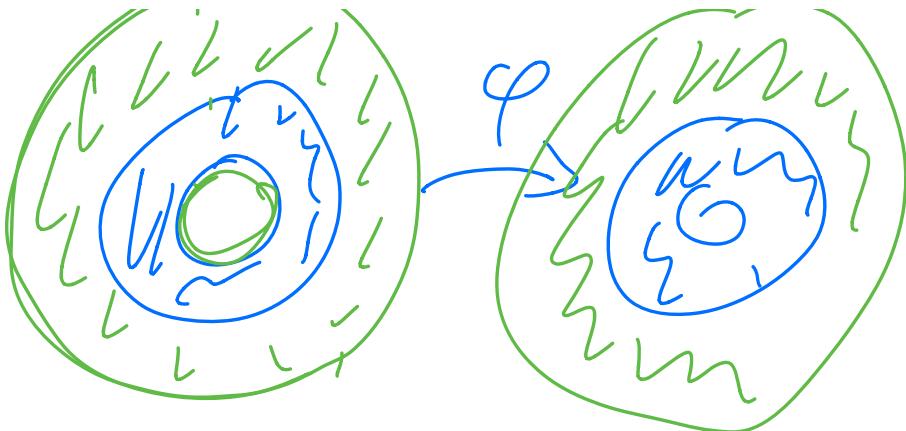
$$= \exp\left(\frac{-2\pi^2}{\log \lambda} + \frac{2\pi i \log|z|}{\log \lambda}\right)$$

$$R = \exp\left(\frac{-2\pi^2}{\log \lambda}\right)$$

$$d_{HI}(i, \lambda_i) = \int_1^{\lambda_i} \frac{dx}{x} = \log \lambda$$

$$A_s^t = \{ s < |z| < t \} \approx \left\{ 1 < |z| < \frac{t}{s} \right\}$$



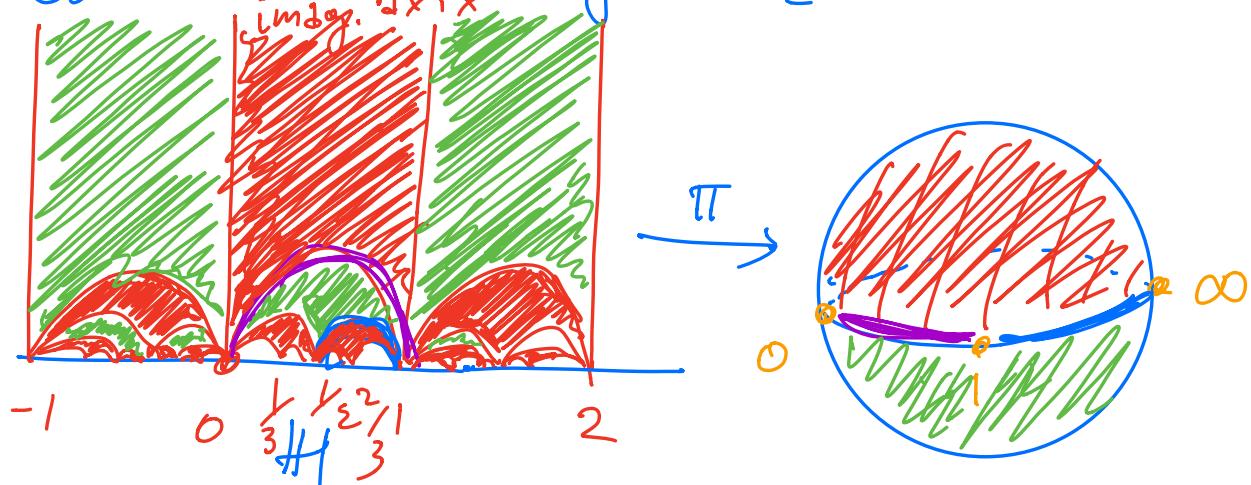


## HYPERBOLIC SURFACES

$$\hat{\mathbb{C}} \setminus \{0, 1, \infty\} \simeq \mathbb{C} \setminus \{0, 1\}$$

$$\mathbb{H} \xrightarrow{\pi} \mathbb{C} \setminus \{0, 1, \infty\}$$

Consider ~~action~~ of  $SL_2(\mathbb{Z})$  on  $\mathbb{H}$



$$\pi(\gamma(z)) = \pi(z) \quad \text{if } \gamma \in SL_2(\mathbb{Z})$$

